

# **Parallel Unsteady Turbopump Flow Simulations For Reusable Launch Vehicles**

**Cetin Kiris  
ELORET**

**and**

**Dochan Kwak  
NASA Ames Research Center**

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- **INTRODUCTION**
  - Major Drivers of the Current Work
  - Objectives
- **APPROACH / PROGRESS**
  - Computational models
  - Code parallelization
  - Time-accuracy and integration schemes
- **SUMMARY**

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## Major Drivers of the Current Work

### ● TOOLS FOR AEROSPACE DESIGN

- Decrease design cycle time      ⇒ Rapid turn-around
- Increase design/process fidelity    ⇒ High accuracy and low variation
- Increase discipline integration    ⇒ Increased range of options via IT

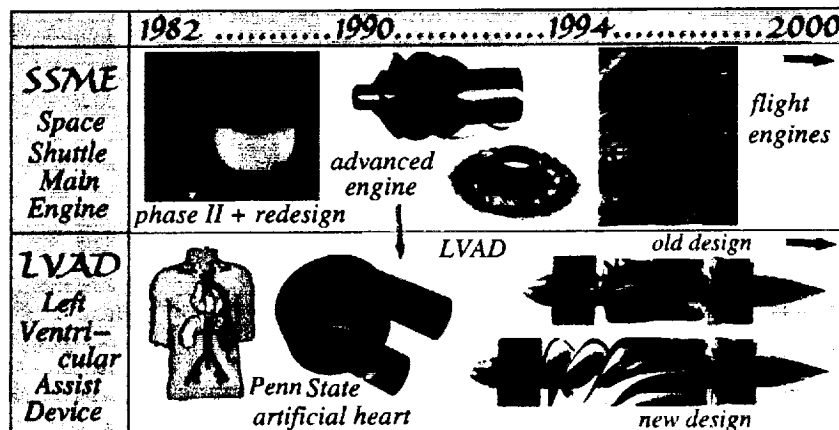
Turbo-pump component analysis    ⇒ Entire turbo pump simulation

### ● HPCC CAS Level I milestone :

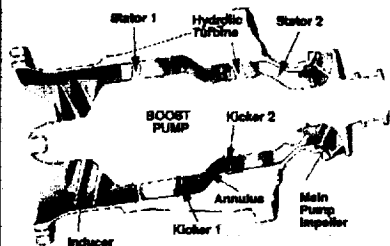
To demonstrate a 1000 times speed up in June 2001 over what was possible in FY92.

## Objectives

- To enhance incompressible flow simulation capability for developing aerospace vehicle components, especially, unsteady flow phenomena associated with high speed turbo pump



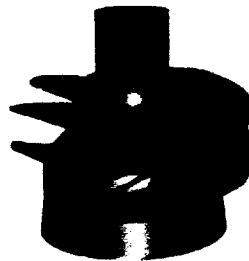
## Computational Model RSTS BOOST PUMP



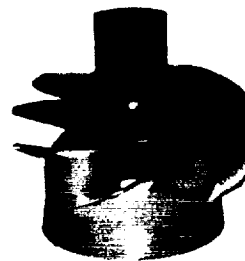
- 1- Inducer (R)
- 2- Stator 1 (S)
- 3- Inducer Kicker (R)
- 4- Annulus (S)
- 5- Kicker (R)
- 6- Hydraulic Turbine (R)
- 7- Stator 2 (S)

### REUSABLE LAUNCH VEHICLE (RLV) TURBOPUMP INDUCER

Rotational Speed : 7850 RPM  
Mass Flow : 9093 GPM  
Re :  $7.90 \times 10^7$



Geometry



Surface Pressure

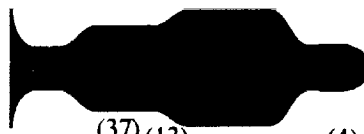
### COMPUTATIONAL CHALLENGES :

- Cost due to time-accurate incompressible flows
- Moving grid system
- Code parallelization

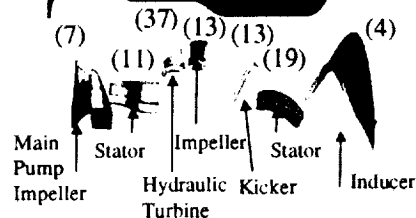
## Boost Pump Computational Model



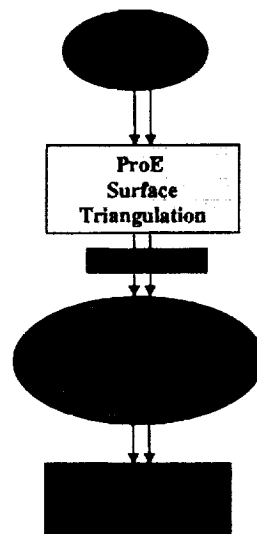
Shroud  
Surface



Hub  
Surface

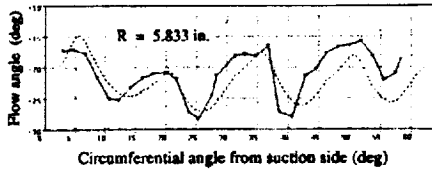
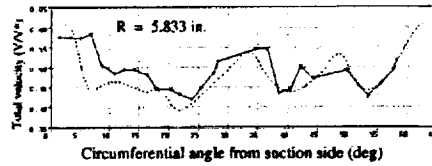
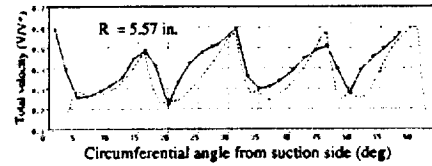


Blades



## SSME Impeller

Pressure



## INS3D Parallelization

Pressure



INS3D-MPI - coarse grain

First release

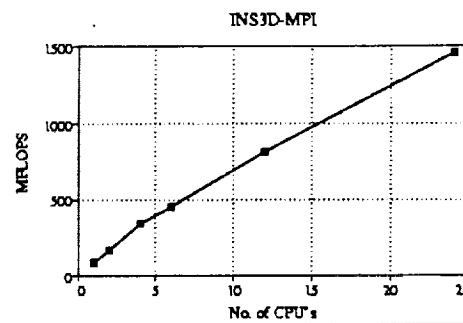
T. Faulkner & J. Dacles

MPI coarse grain + OpenMP

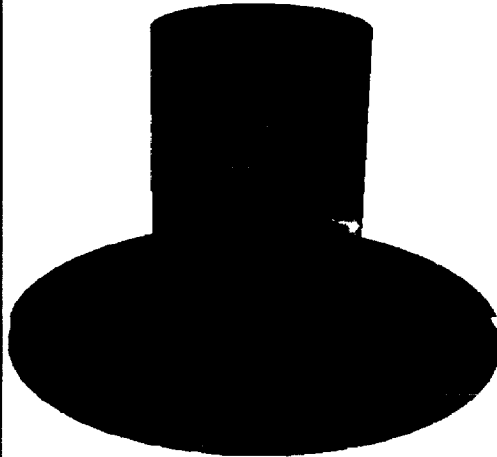
Debugging stage

H. Jin & C. Kiris

MLP (Implementation is currently underway)



## Shuttle Upgrade SSME-rig 1 (code validation)



### Inlet Guide Vane (IGV)

- 15 Blades
- Pitch,  $p = 24$  degrees
- Blade Inlet Angle (mean),  $\beta_{IGV,1} = 90$  degrees
- Blade Exit Angle (mean),  $\beta_{IGV,1} = 45$  degrees

Clearance between IGV and Impeller,  $x = 0.12$  inches

### Impeller

- 6+6+12 Unshrouded Design
- Pitch,  $p = 60$  degrees
- Blade Inlet Angle (mean),  $\beta_{imp,1} = 23$  degrees
- Blade Exit Angle (mean),  $\beta_{imp,1} = 65$  degrees
- Clearance between blade LE and Shroud,  $r = 0.0056$  inches
- Clearance between blade TE and Shroud,  $x = 0.0912$  inches

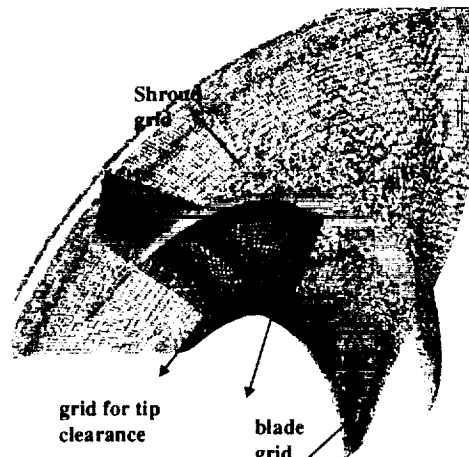
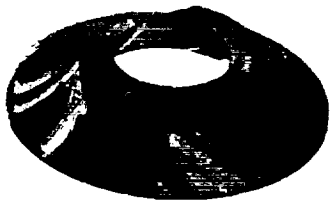
Clearance between Impeller and Diffuser,  $r = 0.050$  inches

### Diffuser

- 23 Blades
- Pitch,  $p = 15.652$  degrees
- Blade Inlet Angle (mean),  $\beta_{diff,1} = 12$  degrees
- Blade Exit Angle (mean),  $\beta_{diff,1} = 43$  degrees

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## Shuttle Upgrade SSME-rig 1



### Unshrouded Impeller Grid :

6 long blades / 6 medium blades / 12 short blades

60 Zones / 19 Million Grid Points

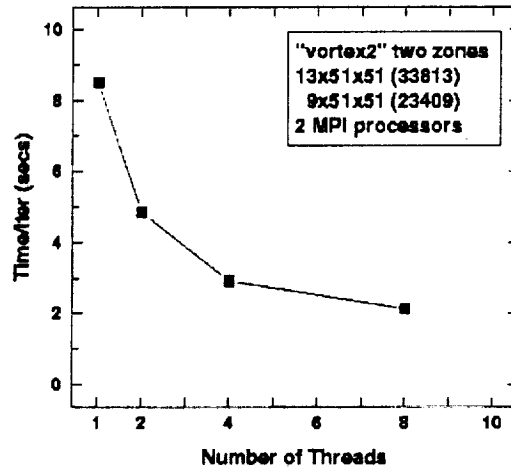
Smallest zone : 74,025 / Largest zone : 899,248

Overset connectivity is obtained by using DCF module OVERFLOW-D

## INS3D Parallelization

MPI coarse grain + OpenMP fine grain

TEST CASE : 2 Zones Vortex

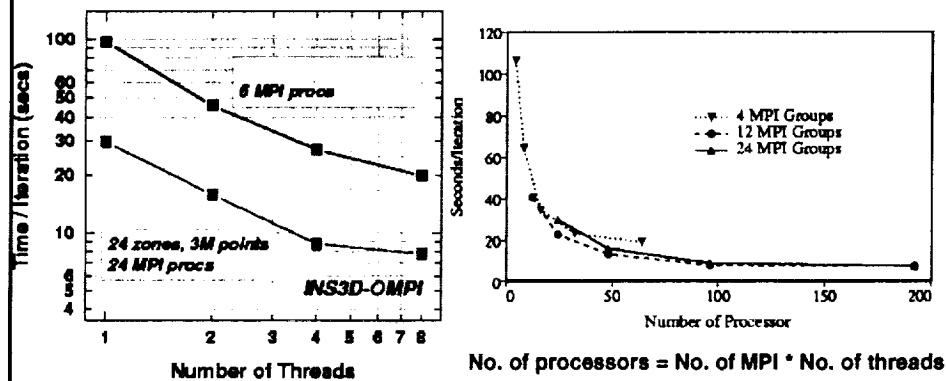


Intel Xeon, Q2K 300 MHz

## INS3D Parallelization

MPI coarse grain + OpenMP fine grain

TEST CASE : SSME Impeller



## Time-Accurate Formulation

- Time-integration scheme

### Artificial Compressibility Formulation

- Introduce a pseudo-time level and artificial compressibility
- Iterate the equations in pseudo-time for each time step until incompressibility condition is satisfied.

### Pressure Projection Method

- Solve auxiliary velocity field first, then enforce incompressibility condition by solving a Poisson equation for pressure.

## Pressure Projection Method

- Evaluate time-accurate features of two primitive variable methods designed for 3-D applications

- Solve for the auxiliary velocity field, using implicit predictor step

$$\frac{1}{\Delta t}(u_i^* - u_i^n) = -\nabla p^n + h(u_i^*)$$

- The velocity field at time level (n+1) is obtained by using a correction step,

$$\frac{2}{\Delta t}(u_i^{n+1} - u_i^*) = -\nabla p^{n+1} + h(u_i^{n+1}) - \nabla p^n + h(u_i^*)$$

- The incompressibility condition is enforced by using a Poisson equation for pressure (  $p = p^{n+1} - p^n$  )

$$\nabla^2 p = \frac{2}{\Delta t} \nabla \cdot \mathbf{u}^*$$

## Pressure Projection Method(INS3D-FS)

- The discretization of the mass conservation equation in finite volume formulations

$$(S^{\xi} \mathbf{u})_{j+1/2} - (S^{\xi} \mathbf{u})_{j-1/2} + (S^{\eta} \mathbf{u})_{k+1/2} - (S^{\eta} \mathbf{u})_{k-1/2} + (S^{\zeta} \mathbf{u})_{l+1/2} - (S^{\zeta} \mathbf{u})_{l-1/2} = 0$$

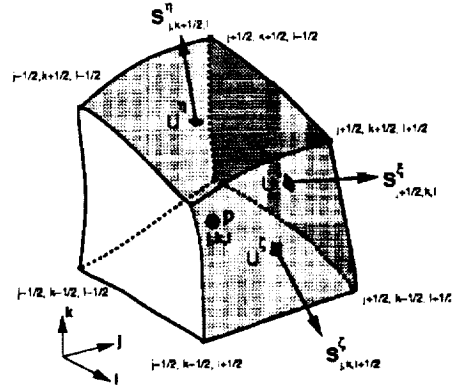
- New dependent variables,

$$U^{\xi} = S^{\xi} \mathbf{u}$$

$$U^{\eta} = S^{\eta} \mathbf{u}$$

$$U^{\zeta} = S^{\zeta} \mathbf{u}$$

- Computing time : 80  $\mu$ -secs/grid point/iteration
- Memory usage: 70 times number of grid points in words



## Artificial Compressibility Method (INS3D-UP)

### Time-Accurate Formulation

- Discretize the time term in momentum equations using second-order three-point backward-difference formula

$$\left( \frac{\partial U}{\partial \xi} + \frac{\partial V}{\partial \eta} + \frac{\partial W}{\partial \zeta} \right)^{n+1} = 0 \quad \frac{3q^{n+1} - 4q^n + q^{n-1}}{2\Delta t} = -r^{n+1}$$

- Introduce a pseudo-time level and artificial compressibility,
- Iterate the equations in pseudo-time for each time step until incompressibility condition is satisfied.

$$\frac{1}{\Delta \tau} (p^{n+1,m+1} - p^{n+1,m}) = -\beta \nabla q^{n+1,m+1}$$

$$\frac{1.5}{\Delta t} (q^{n+1,m+1} - q^{n+1,m}) = -r^{n+1,m+1} - \frac{3q^{n+1,m} - 4q^n + q^{n-1}}{2\Delta t}$$

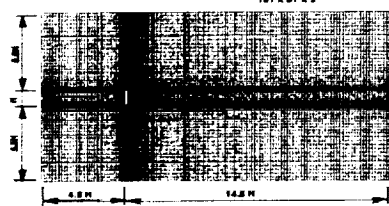
- Computing time : 50-120  $\mu$ -secs/grid point/iteration
- Memory usage: **Line-relaxation** 45 times number of grid point in words  
**GMRES-ILU(0)** 220 times number of grid point in words



## Impulsively Started Flat Plate at 90°

### • GRID

Thickness of plate =  $0.3H$



$T=1.2$



$T=2.0$

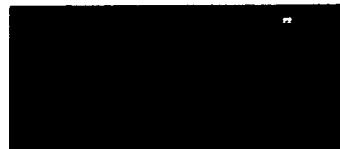


### • VELOCITY MAGNITUDE

$T=0.4$

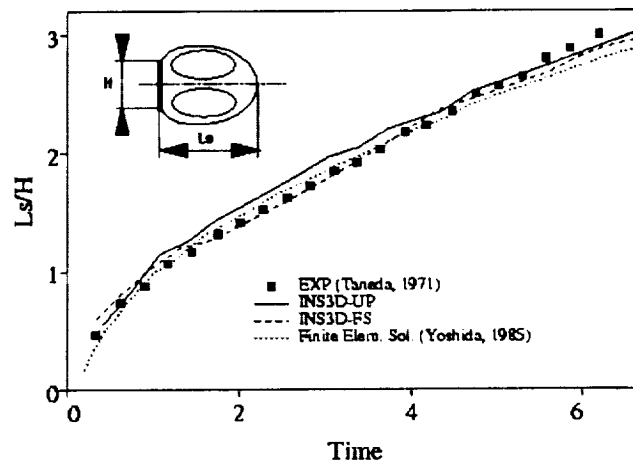


$T=4.0$



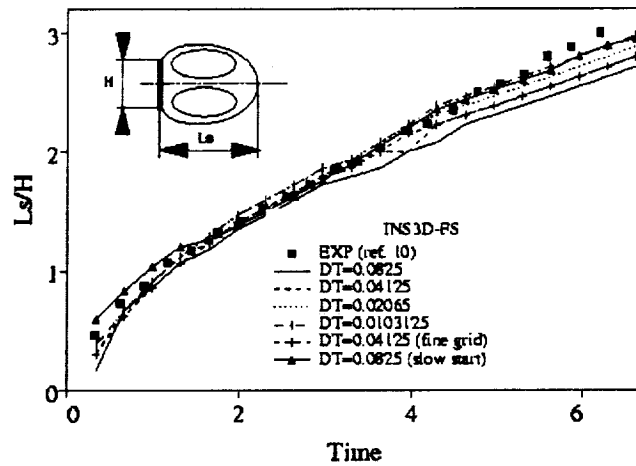
## Impulsively Started Flat Plate at 90°

### • Time History of Stagnation Point



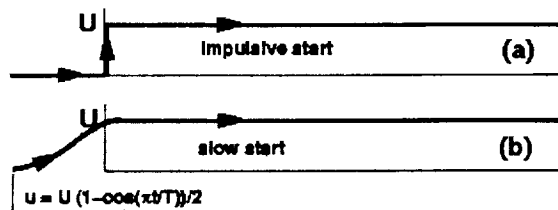
## Impulsively Started Flat Plate at 90°

- Time History of Stagnation Point  
Pressure Projection Method (INS3D-FS)



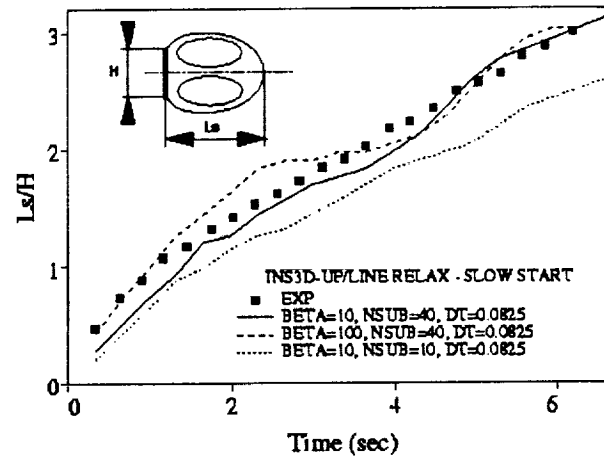
## Impulsively Started Flat Plate at 90°

- Starting procedure



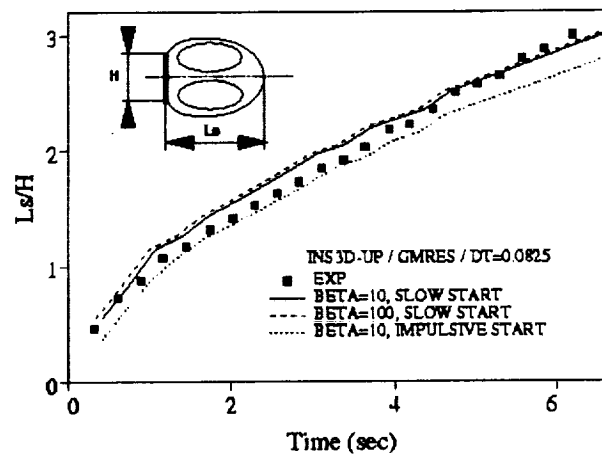
## Impulsively Started Flat Plate at 90°

- Time History of Stagnation Point  
Artificial compressibility (INS3D-UP) : Line Relaxation



## Impulsively Started Flat Plate at 90°

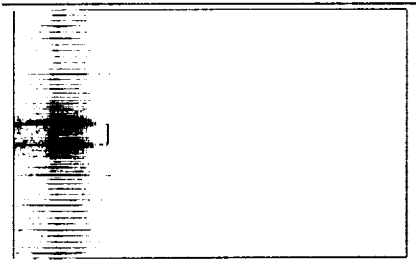
- Time History of Stagnation Point  
Artificial compressibility (INS3D-UP) : GMRES



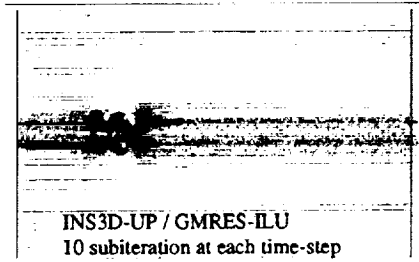
## Impulsively Started Flat Plate at 90°

● VELOCITY VECTORS  $T=0.53$

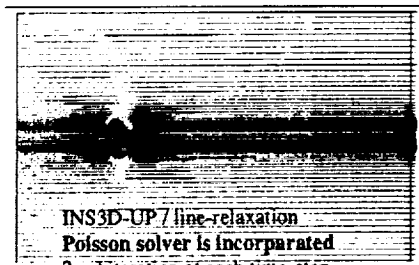
Flow is at rest and  
 $U=1$  imposed at inflow at  $T=0.0$



INS3D-UP line-relaxation  
 10 subiteration at each time-step



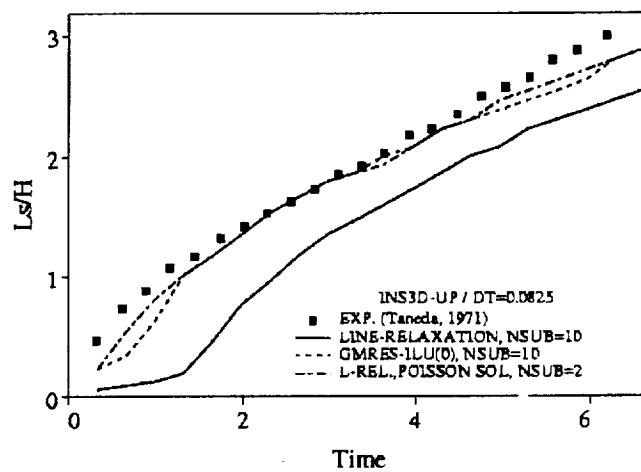
INS3D-UP / GMRES-ILU  
 10 subiteration at each time-step



INS3D-UP / line-relaxation  
 Poisson solver is incorporated  
 2 subiteration at each time-step

## Impulsively Started Flat Plate at 90°

● Time History of Stagnation Point  
 Artificial compressibility incorporated with Poisson solver



## Summary

- An efficient solution procedure for time-accurate solutions of Incompressible Navier-Stokes equation is obtained.
  - Artificial compressibility method requires a fast convergence scheme..
  - Pressure projection method is efficient when small time-step is required.
  - The number of sub-iteration is reduced significantly when Poisson solver is employed with the continuity equation.
  - Both computing time and memory usage are reduced (at least 3 times).
  - DCF module in OVERFLOW-D is incorporated with INS3D.
  - MPI /Open MP hybrid parallel code has been completed and benchmarked.
- Work currently underway
  - Multi Level Parallelism (MLP) of INS3D.
  - Overset connectivity for the validation case (SSME-rig1)
  - Experimental measurements at NASA-MSFC.
  - Computational model for boost pump